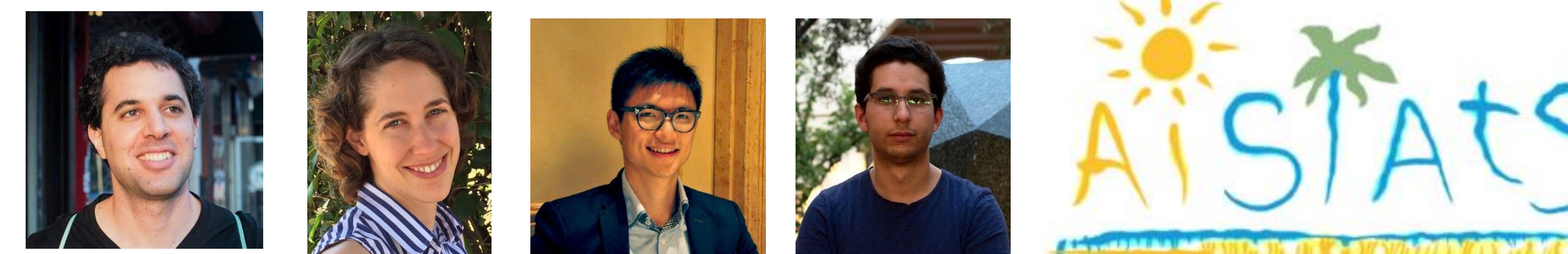


Gaming Helps! Learning from Strategic Interactions in Natural Dynamics

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Gaming

Strategic modification of measurements, which individuals anticipate would positively affect the outcome of a decision rule.

Examples: College admissions, Credit, Insurance, Hiring, ...

Machine learning algorithms are now heavily involved.

Problem: Feature modifications might make individuals appear better than they actually are.

Approaches in prior work:

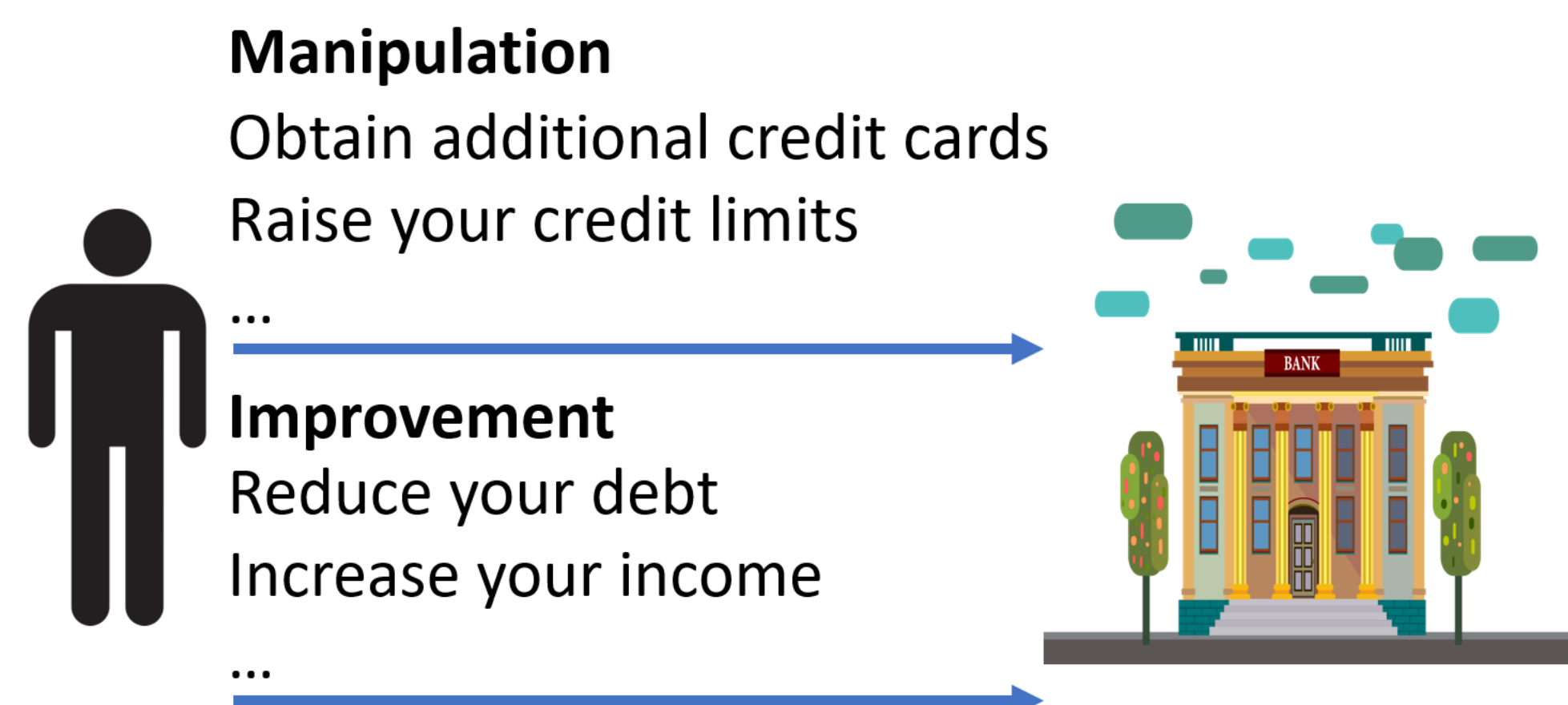
- Obfuscation of decision rule.
 - May leak over time.
 - Individuals can learn from past examples.
- Robustness to gaming.
 - Additional burden on qualified individuals.
 - Cripples ability to recover or improve.

Our Approach

Gaming can be actually be **helpful!**

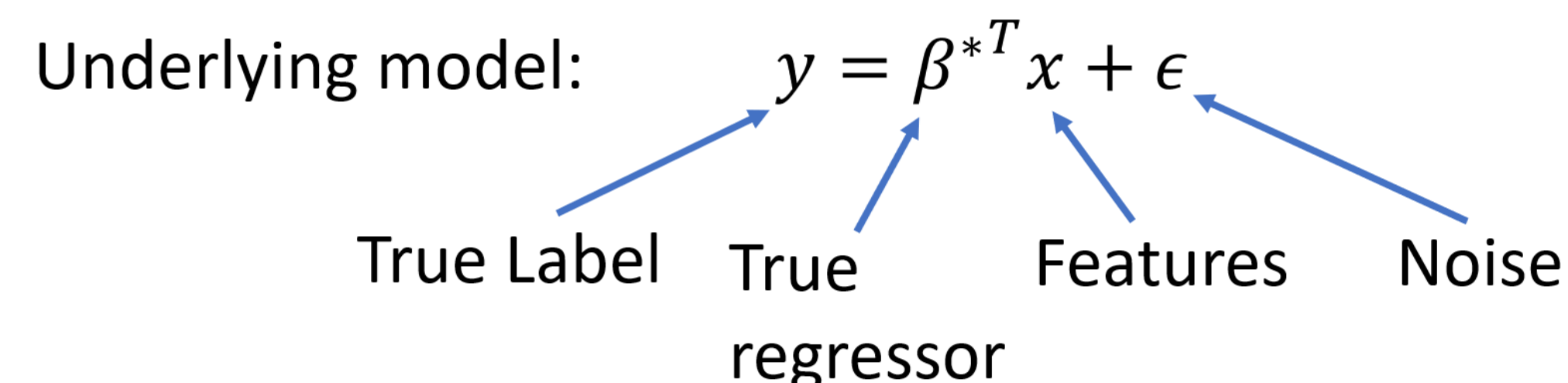
Idea: Distinguish false feature manipulation from improvement.

Manipulation Vs. Improvement



Model

Online. Linear Regression.



Meaningful Vs. Non-meaningful features:

$$\beta^* \in R^d \quad \begin{array}{l} \text{Meaningful:} \quad \beta^*_i \neq 0 \\ \text{Non-Meaningful:} \quad \beta^*_i = 0 \end{array}$$

Algorithms

Algorithm 1: Online Regression with Epoch-Based Strategic modification (Epoch size n)

Learner picks (any) initial $\hat{\beta}_0$.
for every epoch $E \in \mathbb{N}$ **do**
 for $t \in \{(E-1)n+1, \dots, En\}$ **do**
 Agent t reports $\bar{x}_t \in M(\hat{\beta}_{E-1}, c_t, B_t)$.
 Learner observes $\bar{y}_t = \beta^{*T} \bar{x}_t + \epsilon_t$.
 end
 Learner picks $\hat{\beta}_E \in LSE(\tau(E))$.
end

Tie-breaking matters! (Intuition for Algorithm 2)

Weight on meaningful features
 → Incentivize improvements of said features
 → May prevent exploration of remaining features

Solution: put weight in unexplored directions:

- Retains accuracy on directions seen so far
- Incentivizes exploration of unseen directions

Motivation

If distribution over X is not full-rank, recovery of β^* is **impossible**.

Optimizing for $\hat{\beta}$ over a rank-deficient space implies:

- Non-zero weight on non-meaningful features -> Susceptibility to false manipulations.
- Less weight on meaningful features -> Reduced utility.

Results

Our provided algorithm + tie-breaking scheme guarantee:

- Recovery of the true underlying model $\hat{\beta}$.
- Achieving recovery within the confinements of **natural dynamics**.
 At any point, deployed scoring rule projected to the recovered subspace is optimal.

Theorem 5.2 (Recovery Guarantee with Tie-Breaking Scheme (Algorithm 2)). *Suppose the epoch size satisfies $n \geq \frac{\kappa d^2}{\lambda} \sqrt{2T \log(24d/\delta)}$, and take α to be*

$$\alpha \geq \gamma \left(\sqrt{d} + \frac{Kd \sqrt{2T \log(8d/\delta)}}{\lambda n} \right),$$

where $\gamma, K, \kappa, \lambda$ are instance-specific constants that only depend on $\sigma, \mathcal{C}, \Sigma$, and $\lambda > 0$. If $T \geq dn$, we have with probability at least $1 - \delta$ that at the end of the last epoch T/n ,

$$\|\hat{\beta}_{T/n} - \beta^*\|_2 \leq \frac{K \sqrt{2dT \log(8d/\delta)}}{\lambda n},$$

under the tie-breaking rule of Algorithm 2.

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